

Bounded Differences Inequalities for Graph-dependent Random Variables and Stability Bounds

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Bounded Differences Inequality

$$\mathbf{P}(f(\mathbf{X}) - \mathbf{E}[f(\mathbf{X})] \geq t) \leq ?$$

Definition (c-Lipschitz, Bounded Differences Condition)

Given a vector $\mathbf{c} = (c_1, \dots, c_n) \in \mathbb{R}_+^n$, a function f is \mathbf{c} -Lipschitz if

$$|f(x_1, \dots, \mathbf{x}_i, \dots, x_n) - f(x_1, \dots, \mathbf{x}'_i, \dots, x_n)| \leq c_i$$

Theorem (Bounded Differences Inequality [McDiarmid, 1989])

- 1 f is \mathbf{c} -Lipschitz
- 2 $\mathbf{X} = (X_1, \dots, X_n)$ are independent random variables

$$\mathbf{P}(f(\mathbf{X}) - \mathbf{E}[f(\mathbf{X})] \geq t) \leq \exp\left(-\frac{2t^2}{\|\mathbf{c}\|_2^2}\right)$$

also called Azuma-Hoeffding inequality.

Dependent Random Variables

- Mixing coefficients: $\alpha/\beta/\phi/\Phi/\eta$ -mixing, etc.
 - ▶ quantitatively measure the dependence among random variables.
 - ▶ widely used in probability theory, statistical theory.
- Dependency graphs: Lovász Local Lemma, Normal/Poisson approximation, Janson's/Suen's Inequality, etc.
 - ▶ combinatorial, independent set, max degree, cumulant, spanning tree, etc.
- Copula, graphical models (random field, Bayesian network, etc.), statistical physics, time series, etc.



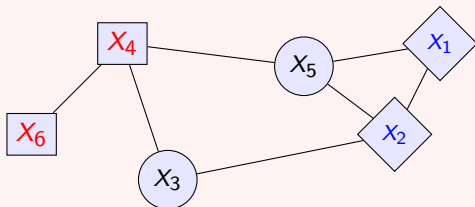
Dependency Graphs

Definition (Dependency Graphs)

G is called a dependency graph for random variables $\mathbf{X} = \{X_1, \dots, X_n\}$ if

- Vertices $V(G) = [n] = \{1, \dots, n\}$ represent random variables X_1, \dots, X_n
- If disjoint $I, J \subset [n]$ are non-adjacent in G , $\{X_i\}_{i \in I}$ and $\{X_j\}_{j \in J}$ are independent.

Example



$\{X_1, X_2\}$ and $\{X_4, X_6\}$ are independent.

- ▶ The dependency graph for a set of random variables is not necessarily unique.
- ▶ There are weaker versions of dependency graphs, e.g. the one used in LLL.



Janson's Hoeffding-type inequality

Theorem ([Hoeffding, 1963])

\mathbf{X} : independent random variables

$$\mathbf{P}\left(\sum_{i=1}^n X_i - \mathbf{E}\left[\sum_{i=1}^n X_i\right] \geq t\right) \leq \exp\left(-\frac{2t^2}{\|\mathbf{c}\|_2^2}\right)$$

Theorem ([Janson, 2004])

\mathbf{X} : graph-dependent random variables

$$\mathbf{P}\left(\sum_{i \in V(G)} X_i - \mathbf{E}\left[\sum_{i \in V(G)} X_i\right] \geq t\right) \leq \exp\left(-\frac{2t^2}{\chi^*(G) \|\mathbf{c}\|_2^2}\right)$$

- ▶ $\chi^*(G)$: fractional chromatic number of dependency graph G for random variables \mathbf{X} .
- ▶ idea: decomposition of summation to **summations over independent set**.
- ▶ Janson has another well-known inequality for dependency graphs.



Tree-Dependent Random Variables

Theorem ([Zhang et al., 2019])

- 1 f is c -Lipschitz
- 2 T is a dependency graph for \mathbf{X} ; T is a tree

$$\mathbf{P}(f(\mathbf{X}) - \mathbf{E}[f(\mathbf{X})] \geq t) \leq \exp\left(-\frac{2t^2}{c_{\min}^2 + \sum_{\{i,j\} \in E(T)} (c_i + c_j)^2}\right)$$

where c_{\min} is the minimum entry of c .



Forest-Dependent Random Variables

Theorem ([Zhang et al., 2019])

- 1 f is c -Lipschitz
- 2 F is a dependency graph for \mathbf{X} ; $F = \{T_i\}_{i \in [k]}$ is a forest

$$\mathbf{P}(f(\mathbf{X}) - \mathbf{E}[f(\mathbf{X})] \geq t) \leq \exp\left(-\frac{2t^2}{\sum_{i=1}^k c_{\min,i}^2 + \sum_{\{i,j\} \in E(F)} (c_i + c_j)^2}\right)$$

where $c_{\min,i} = \min\{c_j : j \in V(T_i)\}$

- ▶ strict generalisation of the McDiarmid's inequality for independent random variables
- ▶ By **transforming graph to forest via merging vertices**, using the notion of Forest Complexity $\Lambda(G)$, we can handle general graph G

$$\exp\left(-\frac{2t^2}{\Lambda(G)c_{\max}^2}\right)$$



Examples

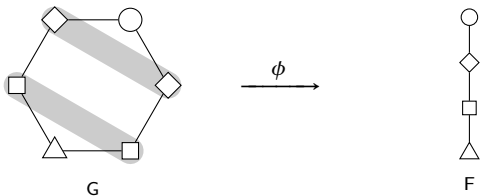


Figure: C_6 : $\Lambda(G) \leq 8n - 13 = O(n)$

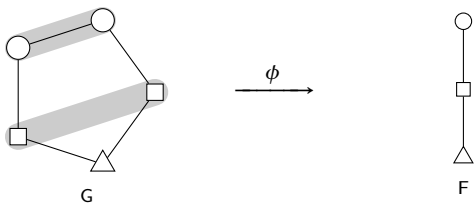


Figure: C_5 : $\Lambda(G) \leq 8n - 14 = O(n)$



Examples

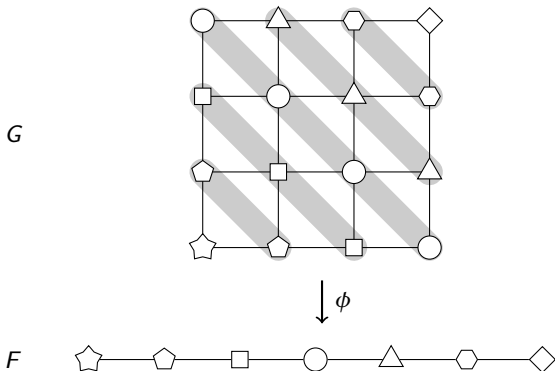


Figure: 4×4 -grid $\Lambda(G) = O(n^{\frac{3}{2}})$



m -dependence

Corollary (m -dependence [Zhang et al., 2019])

Random variables $\{X_j\}_{j=1}^n$ is called m -dependent if for any $i \in [n - m - 1]$, $\{X_j\}_{j=1}^i$ is independent of $\{X_j\}_{j=i+m+1}^n$.

$$\Lambda(G) \leq \left(\left\lceil \frac{n}{m} \right\rceil - 1 \right) (m + m)^2 + m^2 \leq 4mn = O(mn)$$

$$\mathbf{P}(f(\mathbf{X}) - \mathbf{E}[f(\mathbf{X})] \geq t) \leq \exp\left(-\frac{2t^2}{4mnc_{\max}^2}\right)$$

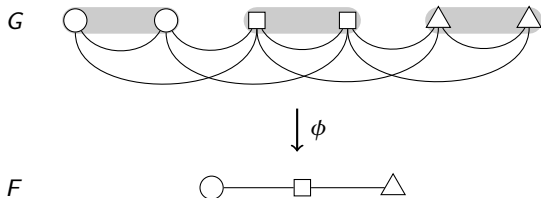


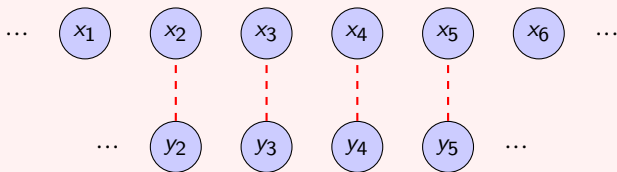
Figure: 2-dependent sequence



Applications in Machine Learning

Example

- y_i : the observation at location i , e.g., the house price
- x_i : the random variable modelling influential factors at location i



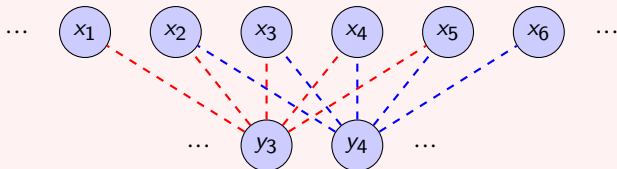
- Given training data: $\mathbf{S} = \{\dots, (x_2, y_2), (x_3, y_3), (x_4, y_4), (x_5, y_5), \dots\}$
- Find predictive function $f : x_i \mapsto y_i$



Applications in Machine Learning

Example

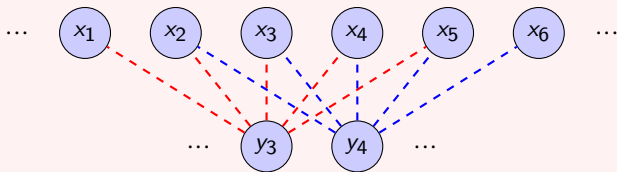
- y_i : the observation at location i , e.g., the house price
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Applications in Machine Learning

Example

- y_i : the observation at location i , e.g., the house price
- x_i : the random variable modelling influential factors at location i



- Given training data: $\mathbf{S} = \{ \dots, ((x_1, x_2, x_3, x_4, x_5), y_3), ((x_2, x_3, x_4, x_5, x_6), y_4), \dots \}$
- Find predictive function $f : (x_{i-2}, x_{i-1}, x_i, x_{i+1}, x_{i+2}) \mapsto y_i$



Background on Machine Learning

- Given input x , choose $f : x \mapsto y$ that perform well on unknown new data.
- A training data set \mathbf{S} contains n samples $(x_i, y_i) \sim D$ (unknown)
- Loss function measures error between true y and predicted $f(x)$

$$(y, f(x)) \mapsto \ell(y, f(x))$$

upper bounded by $M \in \mathbb{R}_+$

- Expected error: expected loss on **new test data** $(x, y) \sim D$ (unknown)

$$R(f) = \mathbf{E}[\ell(y, f(x))]$$

- Empirical error: average loss on given **training data** $(x_i, y_i)_{i=1}^n$ (computable)

$$\hat{R}(f) = \frac{1}{n} \sum_{i=1}^n \ell(y_i, f(x_i))$$

- Goal is to establish generalisation error bounds

$$R(f) \leq \hat{R}(f) + ?$$



Stability Bound for Learning Graph-Dependent Data

A learning algorithm $\mathcal{A} : \mathbf{S} \mapsto f_{\mathbf{S}}^{\mathcal{A}}$ outputs $f_{\mathbf{S}}^{\mathcal{A}}$ given samples \mathbf{S}

Definition (Uniform Stability [Bousquet and Elisseeff, 2002])

The learning algorithm \mathcal{A} is β_n -uniformly stable if

$$\max_{i \in [n]} \left| \ell(y, f_{\mathbf{S}}^{\mathcal{A}}(x)) - \ell(y, f_{\mathbf{S}^{(i)}}^{\mathcal{A}}(x)) \right| \leq \beta_n$$

Lemma

- $R(f_{\mathbf{S}}^{\mathcal{A}}) - \widehat{R}(f_{\mathbf{S}}^{\mathcal{A}})$ is $(4\beta_n + M/n)$ -Lipschitz
- $\mathbf{E} \left[R(f_{\mathbf{S}}^{\mathcal{A}}) - \widehat{R}(f_{\mathbf{S}}^{\mathcal{A}}) \right] \leq 2\beta_{n,\Delta}(\Delta + 1)$, Δ : max degree

Theorem ([Zhang et al., 2019])

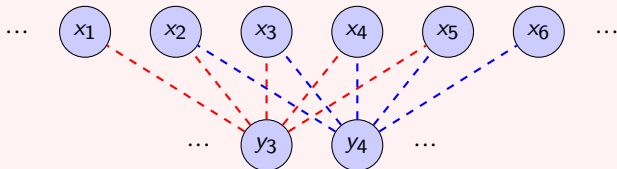
Let $\beta_{n,\Delta} = \max_{i \in [0,\Delta]} \beta_{n-i}$. For $\delta \in (0,1)$, with probability at least $1 - \delta$,

$$R(f_{\mathbf{S}}^{\mathcal{A}}) \leq \widehat{R}(f_{\mathbf{S}}^{\mathcal{A}}) + 2\beta_{n,\Delta}(\Delta + 1) + (4\beta_n + M/n) \sqrt{\frac{\Lambda(G) \ln(1/\delta)}{2}}$$

Stability Bound for Learning m -dependent Data

Example

- y_i : the observation at location i , e.g., the house price
- x_i : the random variable modelling geographical effect at location i



- Given training data: $\mathbf{S} = \{\dots, ((x_1, x_2, x_3, x_4, x_5), y_3), ((x_2, x_3, x_4, x_5, x_6), y_4), \dots\}$
- Find predictive function $f : (x_{i-2}, x_{i-1}, x_i, x_{i+1}, x_{i+2}) \mapsto y_i$

Corollary ([Zhang et al., 2019])

$$R(f_{\mathbf{S}}^{\mathcal{A}}) \leq \widehat{R}(f_{\mathbf{S}}^{\mathcal{A}}) + 2\beta_{n,2m}(2m+1) + (4n\beta_n + M) \sqrt{\frac{2m \ln(1/\delta)}{n}}$$

Future Work

- Improve the results to match the summation bound by Janson.
- Results using other dependency graph models
 - Weighted dependency graphs [Féray et al., 2018]
 - Threshold dependency graphs [Lampert et al., 2018]
- Results for weaker versions of dependency graphs
 - Weak dependency graph: \mathbf{X}_i is independent of $\mathbf{X}_{[n] \setminus N^+(i)}$
 - Pairwise independence: \mathbf{X}_i is independent of $\mathbf{X}_u : u \notin N^+(i)$
- Results for dependency hypergraphs
 - Dependent random variables are generated by independent ones by sharing variables (similar to the variable version Lovász Local Lemma)



- *McDiarmid-type Inequalities for Graph-dependent Variables and Stability Bounds*
Spotlight in Advances in Neural Information Processing Systems 32 (NeurIPS 2019)
- Thanks for your time and attention!



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